

QO100: Clock and supply for LNB and Pluto

Version 4B

for the home station as well as a portable setup we want to minimize the wiring as good as possible.

What we always need:

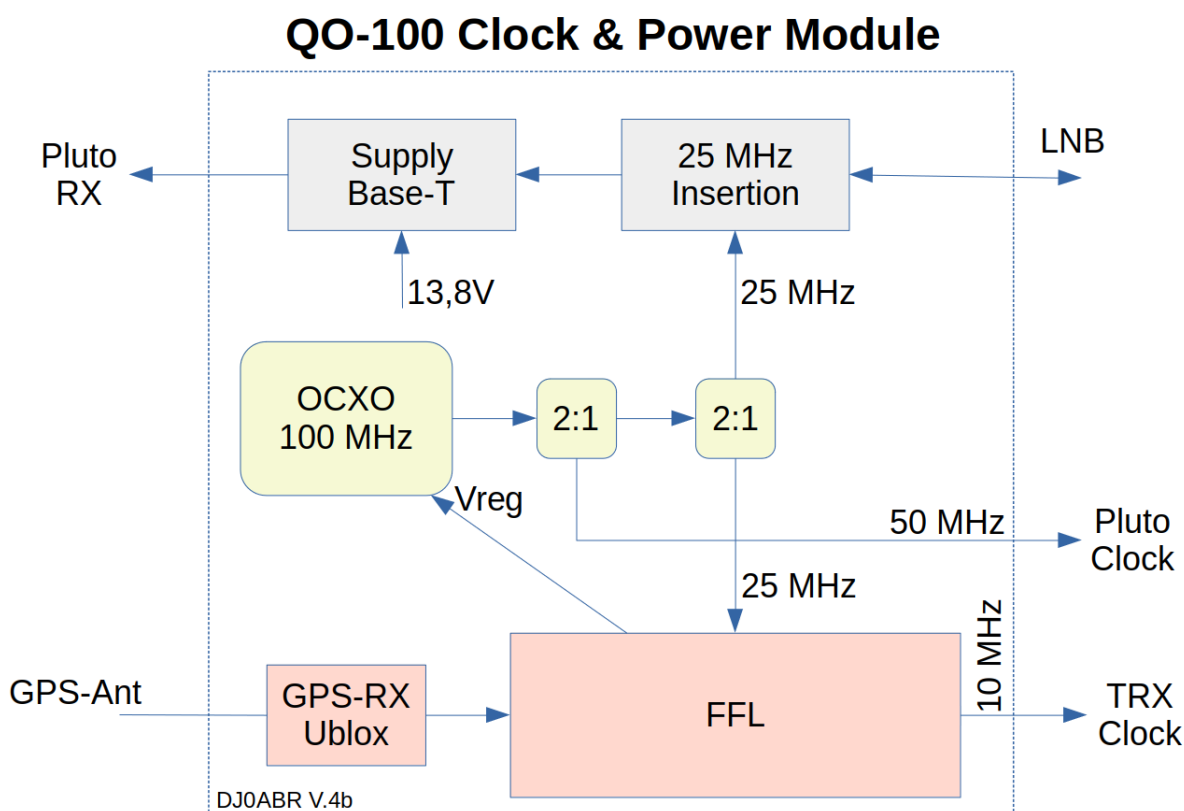
1. Power supply for the LNB via the sat-cable (usually 14V, but 12 to 13,8V is fine)
2. stable 25 MHz reference frequency for the LNB (via the sat-cable or via separate cable)
3. stable reference frequency for the Pluto
4. optional: 10 MHz reference output for TRX (IC9700) or frequency counter

the following circuit solves this task.

Power is supplied from the station power supply or the car battery with 13.8 volts (12V).

The reference clock is generated with a high precision OCXO, which can be optionally GPS stabilized.

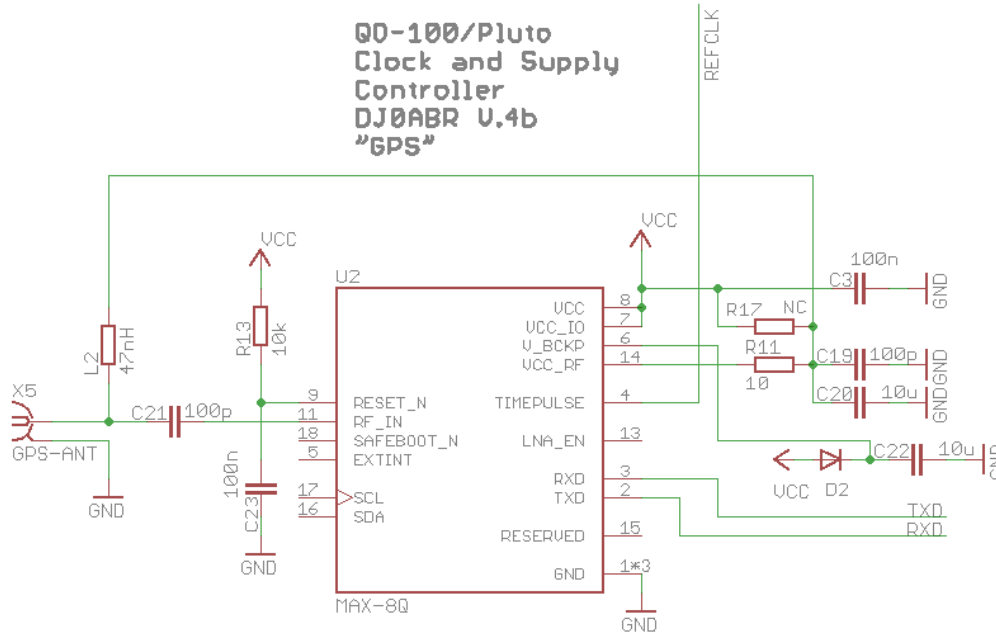
Block diagram:



Clock generation:

The internal supply voltage of 3.3v is generated with a small step-down converter. This is pin compatible with the well known 78xx. If a 78xx type is used, it has to be cooled, while the step-down converter does not need cooling.

GPS receiver:

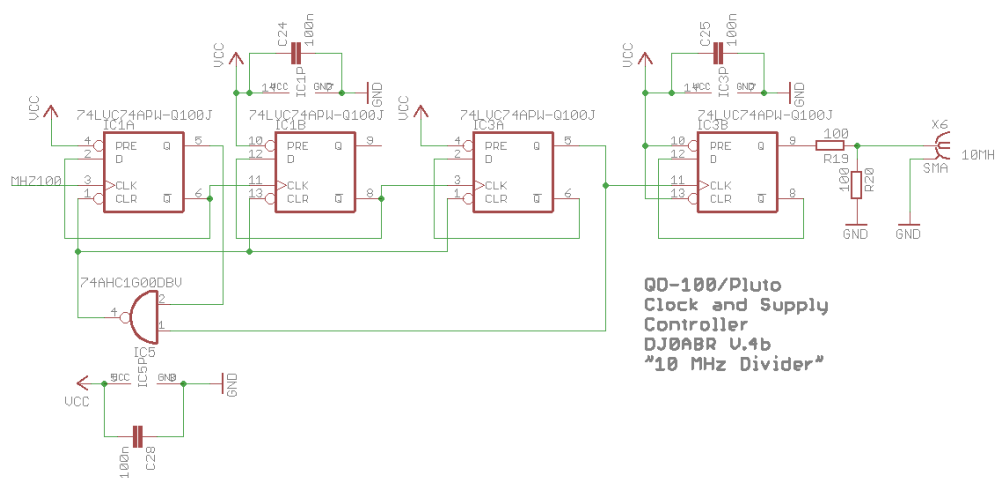


an Ublox MAX-8Q is used. This module is inexpensive and has a programmable reference output (10 MHz).

The highly jittering 10 MHz signal is used by the FFL for stabilization.

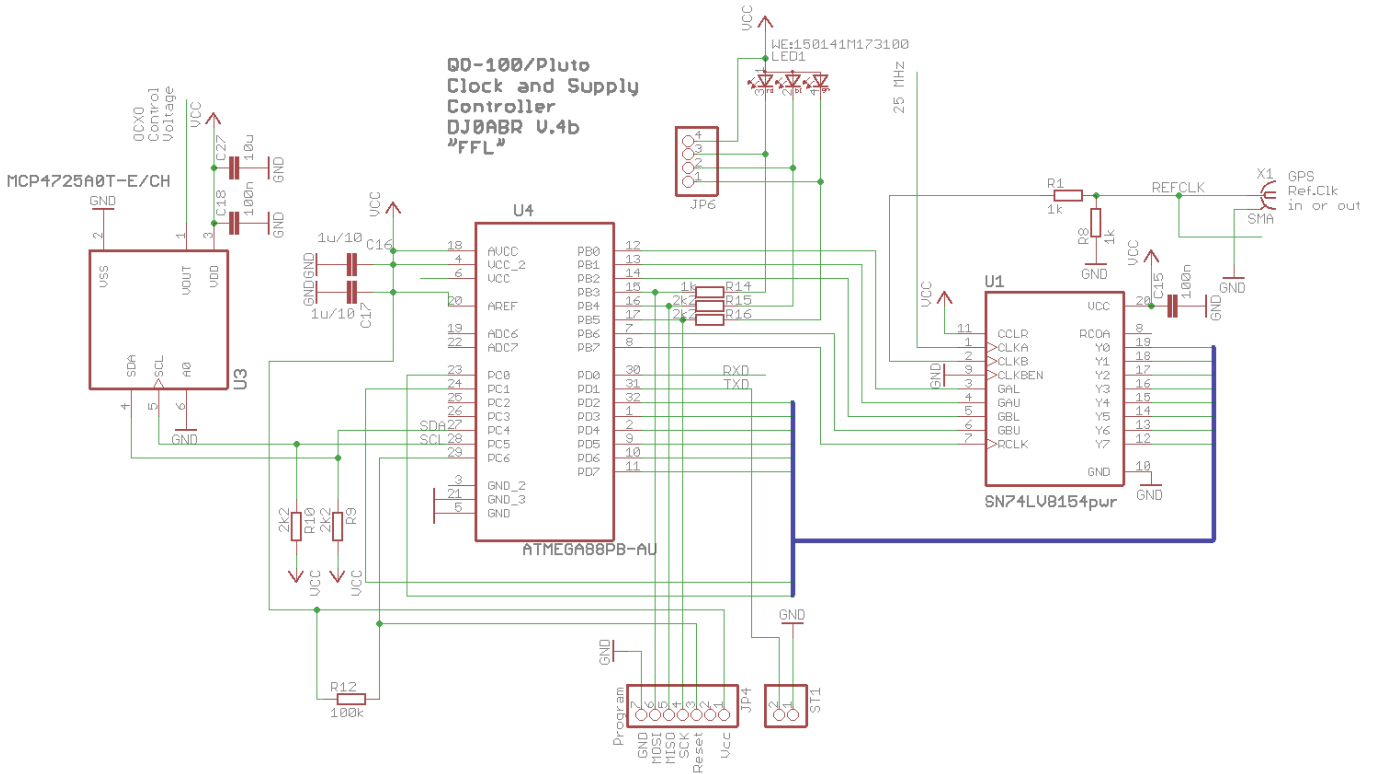
Via the serial interface the Ublox module is set to output the reference frequency when the GPS receive signal is valid.

divider 10 : 1



10 MHz is generated from the 100 MHz OXCO. This frequency can be used for a transceiver (e.g. IC9700) or also frequency counters, etc.

FFL (Frequency Locked Loop):



A 16 bit counter is used to count both the 25 MHz LNB clock and the 10 MHz reference signal. By comparing both signals by software, the actual frequency of the 25 MHz signal is measured, with an accuracy of 0.01Hz. From the deviation a correction value is formed, which fine tunes the OCXO via a 12bit DAC as control voltage.

The 74LV8154 is needed because the uC is not fast enough to count 25 MHz directly. Every 2ms the count is read and then added to the full count value by software.

the board:

After the assembly one measures at the 50 MHz connection with a good frequency counter. With the potentiometer you adjust to exactly 50 MHz. The OCXO has a low aging, so it can be operated for several months without further adjustment. For normal applications on QO-100 it does not need to be adjusted at all. Even after years, the deviation is only a few kHz of the QO-100 receive frequency.

Operation with GPS:

In this case everything is equipped. At the first start-up the potentiometer must be calibrated. To do this, connect the MISO and MOSI lines to pin header JP4, then switch on. Measure the 50 MHz output with a frequency counter and adjust the potentiometer as good as possible to 50 MHz. Then switch off and remove the jumper.

Note that the complete synchronization process can take at least 5 to 10 minutes or longer. With this long loop time you have no additional phase noise and also become independent of the short term quality of the GPS reference (a GPS receiver has excellent long term accuracy but poor short term jitter).

LEDs:

red ... Power indicator. Lights up after a few seconds as soon as the system is ready for operation.

blue ... (only with GPS) lights up as soon as the OCXO is close to the target frequency. Radio operation is now already possible.

green ... (only with GPS) lights up as soon as the OCXO has reached an accuracy of better than 0.4ppb at least once, GPS lock exists.

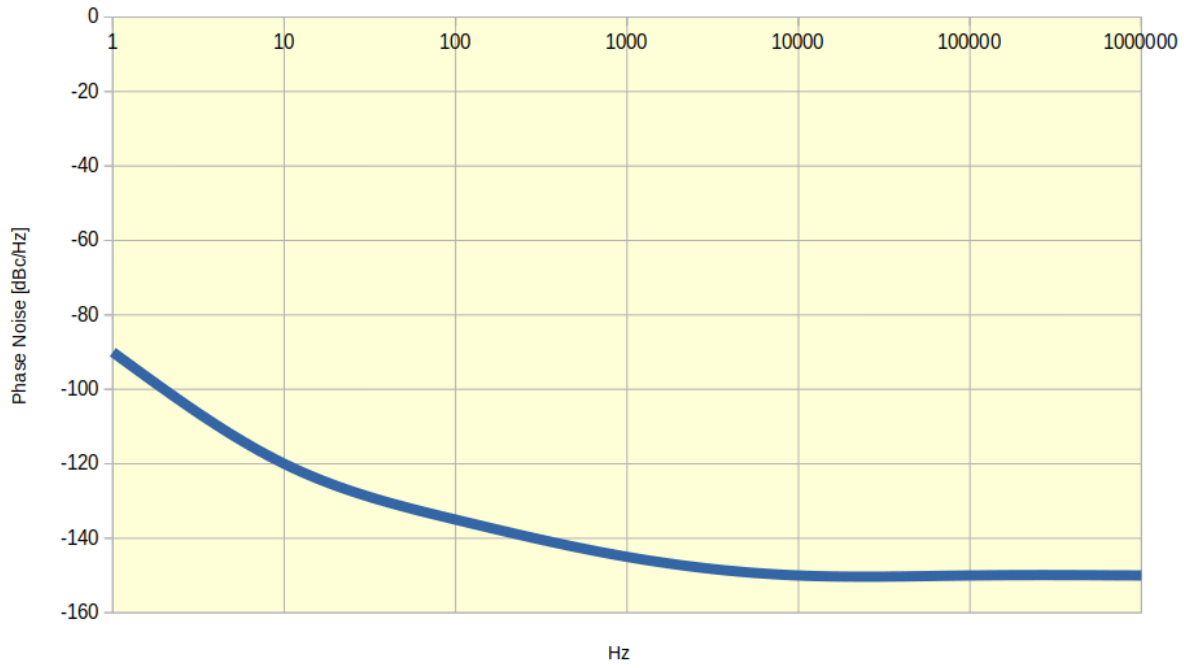
Tips:

if the length of the SAT cable to the LNB is very long (several 10m), the level of the 25 MHz clock can become too small. In this case C6 and C7 are not populated and L1 is replaced by a solder bridge. For extremely long cables you can also replace R6 and R7 with solder bridges, which was necessary for my 80m long SAT cable.

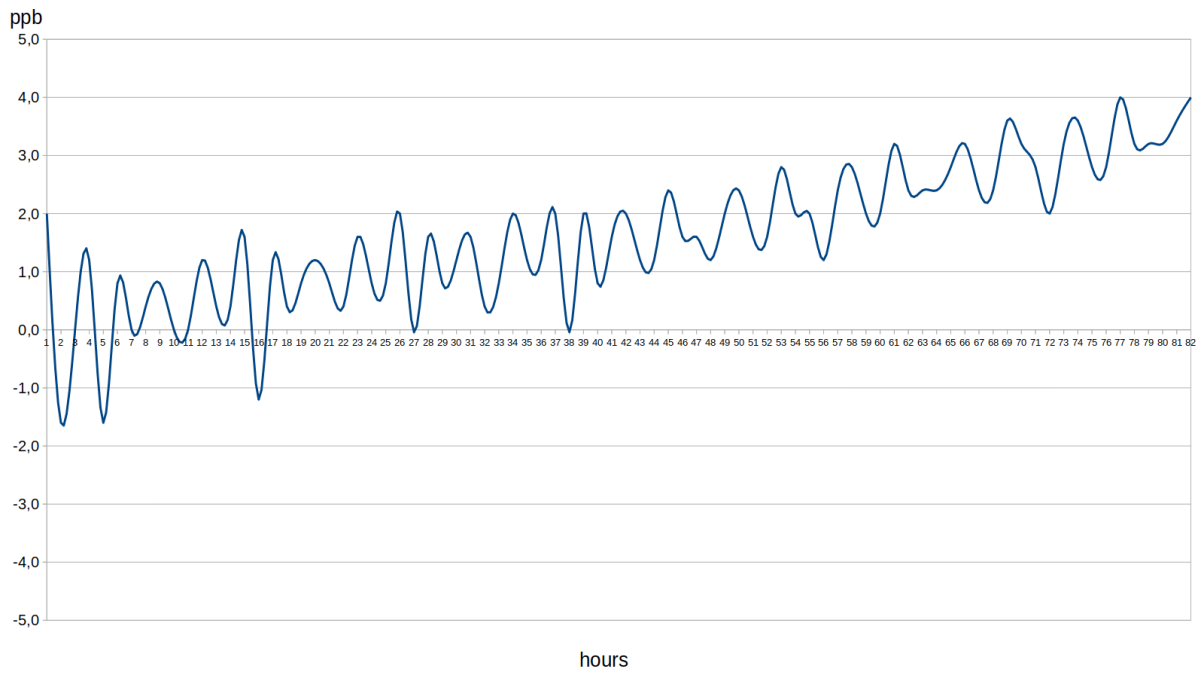
ready assembled device:



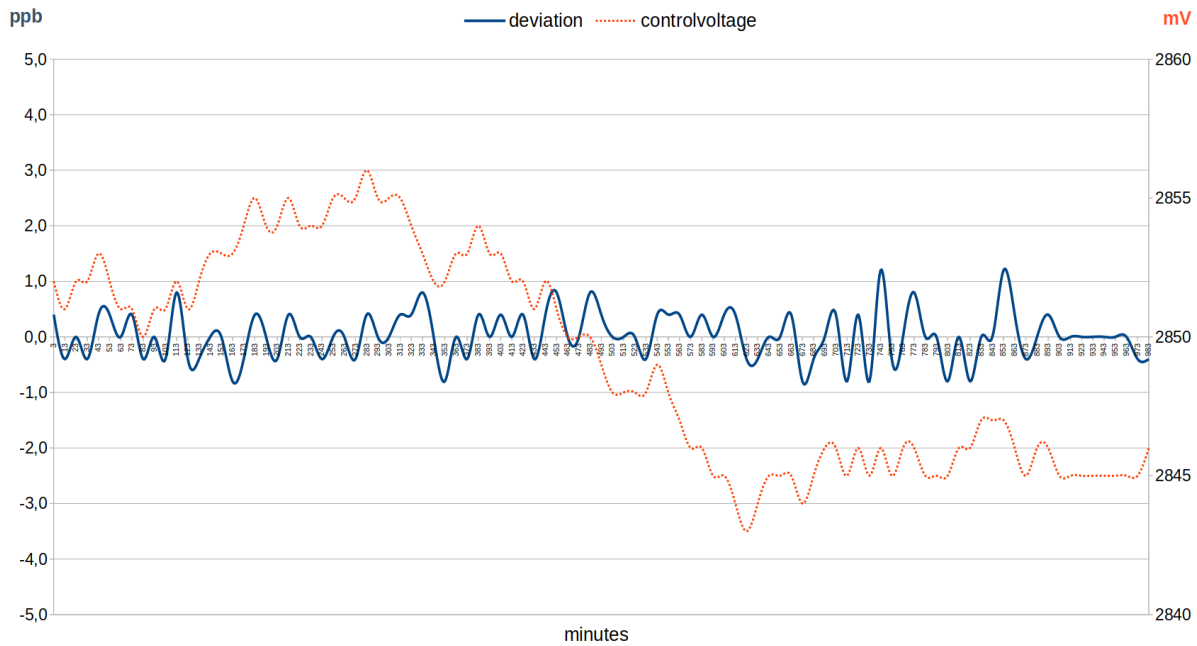
Measurements:



Phase Noise



free running OCXO, still in run-in phase



GPS stabilized OCXO

Downloads:

Eagle Schematics and PCB files

[qo100clock4b.sch.zip](#)

[qo100clock4b.brd.zip](#)

To compile the firmware you need a full installation of avr-gcc (see „comp“), for flashing you need avrdude (see „prg“).

uC and firmware is only required for GPS operation. Pure OCXO operation does not need a microcontroller.

[ocxo_firmware.zip](#)

From: <http://projects.dj0abr.de/> - **DJ0ABR Projects**

Permanent link: <http://projects.dj0abr.de/doku.php?id=en:sat:plutoInb>

Last update: **2024/10/14 11:19**

